EAST Search History

EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S37	17	"5710498"	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 15:08
S38	2	"20060186845"	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 15:17
S39	1555	(318/432).CCLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/21 15:51
S40	55	S39 and position$4 and (correct$4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 15:54
S41	55	S39 and position$4 and (correct$4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 17:20
S42	26	S39 and position$4 and (correct$4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 17:21

S43	10	S39 and position$4 and (correct$4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 17:22
S44	1555	(318/432).CCLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 16:11
S45	10	S44 and position$4 and (correct$4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 16:11
S46	9	S44 and position$4 and (correct$4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf) and ((add$4 sum $4 summation) same (differenc$4 error deviat $4 subtract$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 16:17

S47	9	S44 and position$4 and (correct$4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain$4 and (differenc$4 error deviat$4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf) and ((add$4 sum $4 summation) same (differenc$4 error deviat $4 subtract$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 16:19
S48	4	(("5371361") or ("5790692")).PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 16:21
S49	2	("20080024085").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 16:32
S51	295	"318"/$7.ccls. and position$4 and (correct $4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:34
S52	259	"318"/$7.ccls. and position$4 and (correct $4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain$4 and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf) and ((add$4 sum $4 summation) same (differenc$4 error deviat $4 subtract$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:37

| S53 | 80 | "318"/$7.ccls. and position$4 and (correct $4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain$4 and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf) and ((add$4 sum $4 summation) same (differenc$4 error deviat $4 subtract$4)) and ((filter$4 lpf hpf) same gain$4 same (differenc $4 error deviat$4 subtract $4)) | US-PGPUB; USPAT; EPO; JPO; DERWENT | OR | ON | 2009/10/22 17:40 |
| S54 | 66 | "318"/$7.ccls. and position$4 and (correct $4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain$4 and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf) and ((add$4 sum $4 summation) same (differenc$4 error deviat $4 subtract$4)) and ((filter$4 lpf hpf) same gain$4 same (differenc $4 error deviat$4 subtract $4)) and (torque same (speed velocity)) | US-PGPUB; USPAT; EPO; JPO; DERWENT | OR | ON | 2009/10/22 17:41 |

S55	53	"318"/$7.ccls. and position$4 and (correct $4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain$4 and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf) and ((add$4 sum $4 summation) same (differenc$4 error deviat $4 subtract$4)) and ((filter$4 lpf hpf) same gain$4 same (differenc $4 error deviat$4 subtract $4)) and ((torque same (speed velocity)) same position$4)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:43
S56	47	"318"/$7.ccls. and position$4 and (correct $4 compensat$4) and (feedback (clos$4 adj2 loop)) and gain$4 and (differenc$4 error deviat $4 subtract$4) and (position$4 near9 (correct $4 compensat$4)) and (velocity speed) and torque and (axis axes) and (add$4 sum$4 summation) and (filter$4 lpf hpf) and ((add$4 sum $4 summation) near9 (differenc$4 error deviat $4)) and ((filter$4 lpf hpf) same gain$4 same (differenc$4 error deviat $4 subtract$4)) and ((torque same (speed velocity)) same position $4)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:45
S57	2	("6054827").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 17:48

10/ 24/ 2009 5:24:29 PM
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